

## Solution 1:

- (a)  $L = T - V$  with (i) kinetic term  $T = \sum_{n=1}^N \frac{1}{2} m \dot{\phi}_n^2(t)$ , as the kinetic energy of all point particles simply adds up, and (ii) elastic term  $V = \sum_{n=1}^N \frac{1}{2} k_s (\phi_{n+1} - \phi_n)^2$ , as the potential energy of all springs add up and  $|\phi_{n+1} - \phi_n|$  is identical to the elongation/compression of the spring, i.e., the deviation from the equilibrium length.

(b)

$$0 = \frac{d}{dt} \frac{\partial L}{\partial \dot{\phi}_n} - \frac{\partial L}{\partial \phi_n} = m \ddot{\phi}_n + k_s (2\phi_n - \phi_{n-1} - \phi_{n+1}),$$

because

$$\begin{aligned} \frac{\partial}{\partial \phi_n} \sum_{j=1}^N \frac{1}{2} k_s (\phi_{j+1} - \phi_j)^2 &= \sum_{j=1}^N \frac{1}{2} k_s (2\phi_{j+1} \delta_{n,j+1} - 2\phi_j \delta_{n,j+1} - 2\phi_{j+1} \delta_{n,j} + 2\phi_j \delta_{n,j}) \\ &= \frac{1}{2} k_s (2\phi_n - 2\phi_{n-1} - 2\phi_{n+1} + 2\phi_n). \end{aligned}$$

- (c)  $a$  becomes so small that  $\sum_{n=1}^N \rightarrow \frac{1}{a} \int_0^{L=Na} dx$ . Thus

$$L = \frac{1}{a} \int_0^L dx \left( \frac{1}{2} m (\sqrt{a} \dot{\phi}(x, t))^2 - \frac{1}{2} k_s (\sqrt{a} \phi(x+a, t) - \sqrt{a} \phi(x, t))^2 \right).$$

Employing the Taylor expansion  $\phi(x \pm a, t) = \phi(x, t) \pm a\phi'(x, t) + \frac{1}{2} a^2 \phi''(x, t) + \dots$  one gets

$$L = \int_0^L dx \mathcal{L}, \quad \mathcal{L} = \frac{1}{2} m \dot{\phi}^2(x, t) - \frac{1}{2} k_s a^2 (\phi'(x, t))^2.$$

The Taylor expansion is also used for the equation of motion (e.o.m.):

$$\begin{aligned} 0 &= m \sqrt{a} \ddot{\phi}(x, t) + k_s \sqrt{a} (2\phi(x, t) - \phi(x-a, t) - \phi(x+a, t)) \\ &= \sqrt{a} \left( m \ddot{\phi}(x, t) + k_s (2\phi(x, t) - \phi(x, t) + a\phi'(x, t) - \frac{1}{2} a^2 \phi''(x, t) - \phi(x, t) - a\phi'(x, t) - \frac{1}{2} a^2 \phi''(x, t)) \right) \\ &= \sqrt{a} \left( m \ddot{\phi}(x, t) - k_s a^2 \phi''(x, t) \right). \end{aligned}$$

In terms of  $\partial_t \equiv \partial/\partial t$  and  $\partial_x \equiv \partial/\partial x$  this becomes:

$$\mathcal{L}(\phi, \partial_t \phi, \partial_x \phi) = \frac{1}{2} m (\partial_t \phi)^2 - \frac{1}{2} k_s a^2 (\partial_x \phi)^2 \quad \text{and} \quad m \left( \partial_t^2 - \frac{k_s a^2}{m} \partial_x^2 \right) \phi(x, t) = 0.$$

- (d) In the Euler-Lagrange equation  $\partial_t \frac{\partial \mathcal{L}}{\partial (\partial_t \phi)} + \partial_x \frac{\partial \mathcal{L}}{\partial (\partial_x \phi)} - \frac{\partial \mathcal{L}}{\partial \phi} = 0$  the last term vanishes, the first two terms give directly

$$m \partial_t^2 \phi(x, t) - k_s a^2 \partial_x^2 \phi(x, t) = 0.$$

- (e) The solutions are of the form  $\phi_+(x + v_p t) + \phi_-(x - v_p t)$ , i.e. phonons (sound waves) moving to the left or right with speed  $v_p = a \sqrt{k_s/m}$ .

- (f) In mechanics one has the Hamiltonian  $H(p, q) = p\dot{q} - L$  with the momentum  $p = \frac{\partial L}{\partial \dot{q}}$ , in field theory the Hamiltonian density  $\mathcal{H} = \pi \dot{\phi} - \mathcal{L}$  with the momentum field  $\pi = \partial \mathcal{L} / \partial \dot{\phi}$ .

Here one has  $\pi(x, t) = m \dot{\phi}(x, t)$  and therefore

$$\mathcal{H}(\phi, \pi, \partial_x \phi) = m \dot{\phi}^2 - \frac{1}{2} m \dot{\phi}^2 + \frac{1}{2} k_s a^2 (\partial_x \phi)^2 = \frac{\pi^2}{2m} + \frac{1}{2} m v_p^2 (\partial_x \phi)^2.$$

## Solution 2:

The action of electrodynamics is given by  $S = \int d^4x \mathcal{L} = \int d^4x \left(-\frac{1}{4}F_{\mu\nu}F^{\mu\nu}\right)$  with the anti-symmetric rank-2 tensor (field strength tensor)  $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$ . Note that this tensor (and thus the action) depends only on the derivative of the gauge field and not on the gauge field directly, i.e.,  $\partial\mathcal{L}/\partial A_\mu = 0$ . Furthermore,  $\partial_\mu = \frac{\partial}{\partial x^\mu}$  is the derivative w.r.t. the contravariant coordinate vector  $x^\mu$  and is (in flat space-time) a covariant vector. It has the properties  $\partial_0 = \partial/\partial t$  and  $\partial_i = \partial/\partial x^i = \nabla^i$  for  $i = 1, 2, 3$ .

The Euler-Lagrange equation reads therefore

$$\partial_\alpha \frac{\partial\mathcal{L}}{\partial(\partial_\alpha A_\beta)} - \frac{\partial\mathcal{L}}{\partial A_\beta} = \partial_\alpha \frac{\partial\mathcal{L}}{\partial(\partial_\alpha A_\beta)} = 0.$$

First we write  $F_{\mu\nu}F^{\mu\nu} = F_{\mu\nu}F_{\rho\sigma}g^{\mu\rho}g^{\nu\sigma}$  and note that

$$\begin{aligned} \frac{\partial\mathcal{L}}{\partial(\partial_\alpha A_\beta)} &= -\frac{1}{4} \left( \frac{\partial}{\partial(\partial_\alpha A_\beta)} (\partial_\mu A_\nu - \partial_\nu A_\mu) \right) F_{\rho\sigma} g^{\mu\rho} g^{\nu\sigma} - \frac{1}{4} F_{\mu\nu} \left( \frac{\partial}{\partial(\partial_\alpha A_\beta)} (\partial_\rho A_\sigma - \partial_\sigma A_\rho) \right) g^{\mu\rho} g^{\nu\sigma} \\ &= -\frac{1}{4} (\delta_\mu^\alpha \delta_\nu^\beta - \delta_\nu^\alpha \delta_\mu^\beta) F^{\mu\nu} - \frac{1}{4} F^{\rho\sigma} (\delta_\rho^\alpha \delta_\sigma^\beta - \delta_\sigma^\alpha \delta_\rho^\beta) = -\frac{1}{4} (F^{\alpha\beta} - F^{\beta\alpha}) - \frac{1}{4} (F^{\alpha\beta} - F^{\beta\alpha}) = -F^{\alpha\beta}, \end{aligned} \quad (1)$$

where  $F^{\alpha\beta} = -F^{\beta\alpha}$  has been used. This then leads to the compact Euler-Lagrange equation

$$\partial_\alpha F^{\alpha\beta} = 0. \quad (2)$$

This equation is a four-vector equation. To decompose it into temporal and spatial components we note first that

$$(F^{\alpha\beta}) = \begin{pmatrix} 0 & -E^1 & -E^2 & -E^3 \\ E^1 & 0 & -B^3 & B^2 \\ E^2 & B^3 & 0 & -B^1 \\ E^3 & -B^2 & B^1 & 0 \end{pmatrix},$$

i.e., we have  $F^{00} = 0$ ,  $F^{0i} = -E^i$ ,  $F^{ij} = -\epsilon^{ijk} B^k$ . Now we set  $\beta = 0$  in eq. (2) to obtain Gauss' law:

$$0 = \partial_\alpha F^{\alpha 0} = \partial_i F^{i0} = \partial_i E^i = \vec{\nabla} \cdot \vec{E},$$

where  $i = 1, 2, 3$  has been summed over. Setting now  $\beta = j = 1, 2, 3$  in eq. (2) gives

$$0 = -\partial_\alpha F^{\alpha j} = -\partial_0 F^{0j} - \partial_i F^{ij} = \partial_0 E^j + \partial_i \epsilon^{ijk} B^k = \frac{\partial E^j}{\partial t} - (\vec{\nabla} \times \vec{B})^j.$$

The Maxwell equations  $\vec{\nabla} \cdot \vec{B} = 0$  and  $\partial \vec{B} / \partial t + \vec{\nabla} \times \vec{E} = \vec{0}$  can be derived directly from the definitions and the antisymmetry of  $\epsilon^{ijk}$ :

$$\vec{\nabla} \cdot \vec{B} = \partial_k B^k = -\frac{1}{2} \partial_k \epsilon^{ijk} F^{ij} = \frac{1}{2} \epsilon^{ijk} (\partial^k \partial^i A^j - \partial^k \partial^j A^i) = 0,$$

$$\frac{\partial B^k}{\partial t} + (\vec{\nabla} \times \vec{E})^k = -\frac{1}{2} \epsilon^{ijk} \partial^0 F^{ij} - \epsilon^{ijk} \partial_i F^{0j} = \epsilon^{ijk} \left( \frac{1}{2} \partial^0 \partial^j A^i + \frac{1}{2} \partial^0 \partial^i A^j - \partial^i \partial^j A^0 \right) = 0.$$

Alternatively this can be written as

$$\partial_\alpha \tilde{F}^{\alpha\beta} \equiv \partial_\alpha \frac{1}{2} \epsilon^{\alpha\beta\mu\nu} F_{\mu\nu} = \frac{1}{2} \epsilon^{\alpha\beta\mu\nu} (\partial_\alpha \partial_\mu A_\nu - \partial_\alpha \partial_\nu A_\mu) = 0,$$

in terms of the totally antisymmetric tensor  $\epsilon^{\alpha\beta\mu\nu}$ , whose non-zero components are given by  $+1/-1$  for  $(\alpha\beta\mu\nu)$  being an even/odd permutation of (0123). The tensor  $\tilde{F}^{\alpha\beta}$  is called the dual field strength tensor.